



Case Studies: Projects for Series Vehicles

Embedded Software and ECU Projects

Sensor and Actuator Drivers for an Engine ECU

The Challenge

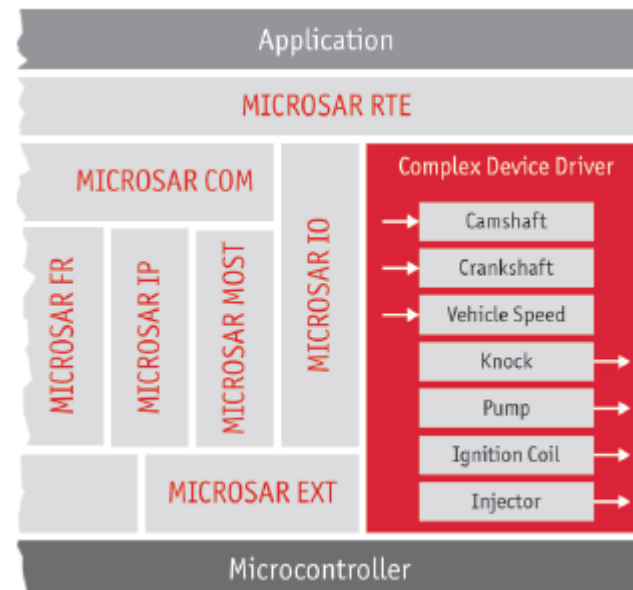
- ▶ Introduction of AUTOSAR 4 software for an engine control unit

The Benefit

- ▶ Vector AUTOSAR 4 solution as SWOTS
- ▶ AUTOSAR compliant software architecture
- ▶ AUTOSAR software drivers (CDDs) as a basis for the application software development
- ➔ Know-how transfer and development of Complex Device Drivers

The Solution

- ▶ Usage of Vector AUTOSAR 4 basic software
- ▶ Additional development of AUTOSAR complex drivers (CDDs) for:
 - ▶ Sensors: Camshaft, crankshaft, vehicle speed, knock detection, misfire detection
 - ▶ Actuators: Engine speed, ignition coil, pump, fuel injectors
- ▶ Consulting for software architecture, on-site integration and AUTOSAR configuration support



On-board Tester for Head Unit ECU

The Challenge

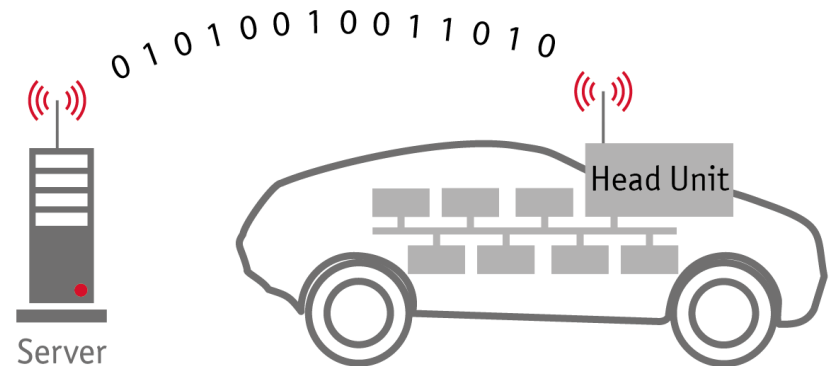
- ▶ Introduction of “over the air” access for in vehicle diagnostics data
- ▶ Head unit ECU shall act as an vehicle internal UDS diagnostics tester
- ▶ AUTOSAR 3 only specifies one UDS server per ECU → additional UDS client (on-board tester) required

The Benefit

- ▶ Detailed knowledge of Vector AUTOSAR 3 solution leads to fast and efficient implementation due to
 - ▶ Vectors expertise in basic software
 - ▶ Project specific implementation

The Solution

- ▶ Development of an “on-board tester” client software component (SWCs) including detection of external car-workshop tester
- ▶ Joint on-site integration



Faster End of Line Flash-Download of a LIN Slave ECU

The Challenge

- ▶ Integration of a CANbedded LIN slave stack into an AUTOSAR environment
- ▶ Diagnostics via AUTOSAR CAN and CANbedded LIN
- ▶ Integration of two flash bootloaders (CAN and LIN) for mutual updates

The Benefit

- ▶ LIN slave ECU as AUTOSAR system
- ▶ High-speed flashing via private CAN in production
- ▶ Re-flashing of ECU in the field via LIN slave capabilities

The Solution

- ▶ Implementation of a complex driver to connect the CANbedded LIN slave stack to an AUTOSAR ECU
- ▶ Implementation of a specific component to connect the AUTOSAR PduR with LIN TP (CANbedded slave)
- ▶ Usage of hardware specific boot mode header for reset safety
- ▶ Cascaded start of CAN and LIN flash bootloaders



Elec. AC Compressor ECU for HD Machines

The Challenge

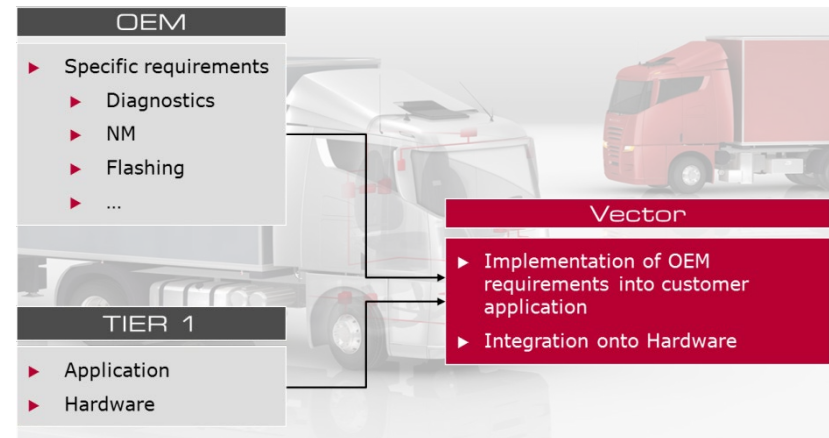
- ▶ Integrate customer application (OEM independent) into ECU software
- ▶ Development of complete firmware (incl. BSW)
- ▶ Provide automated test solution

The Benefit

- ▶ Reuse of application through OEM independent software design
- ▶ Basic software and OEM-specific know-how is not required at customer site
- ▶ System testing with Vector in-house test solution

The Solution

- ▶ Configuration und implementation of BSW
- ▶ Creation of diagnostic specifications
 - ▶ Fault memory
 - ▶ Diagnostic tables
- ▶ Start-up of complete system
- ▶ All parties committed to Vector test solution



Network Controller for a Telematics ECU

The Challenge

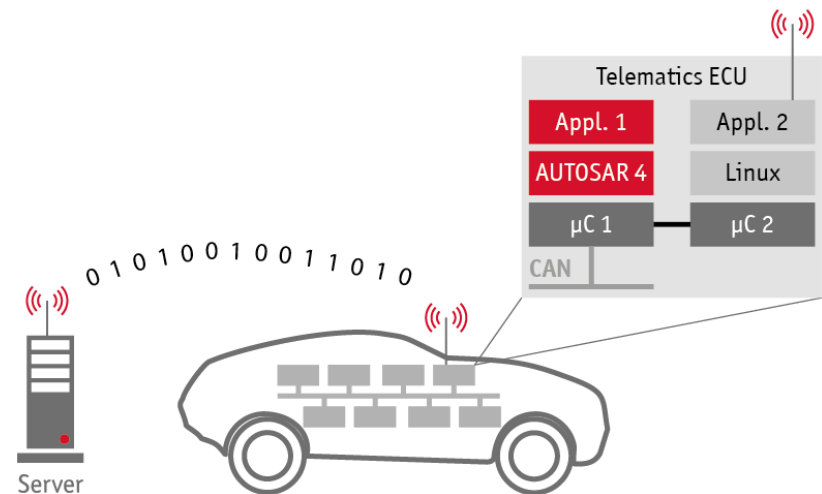
- ▶ Telematics ECU with a 2-controller architecture (mobile phone application controller, vehicle network controller)
- ▶ Customer has high expertise in mobile phone applications
- ▶ Vehicle network specific (BSW) know-how required

The Benefit

- ▶ Combination of domain specific know-how in a cooperation for ECU software development
 - ▶ Faster implementation
 - ▶ High quality due to domain specific expertise

The Solution

- ▶ Vector develops complete SW for network controller including automated test
- ▶ Functions of network controller (ASR 4):
 - ▶ CAN/Ethernet communication and routing
 - ▶ UDS diagnostics
 - ▶ Power management of complete ECU
 - ▶ HW self diagnostics for sensors and actuators
 - ▶ Flash download via CAN/Ethernet, over the air



Battery Cut-off Switch

The Challenge

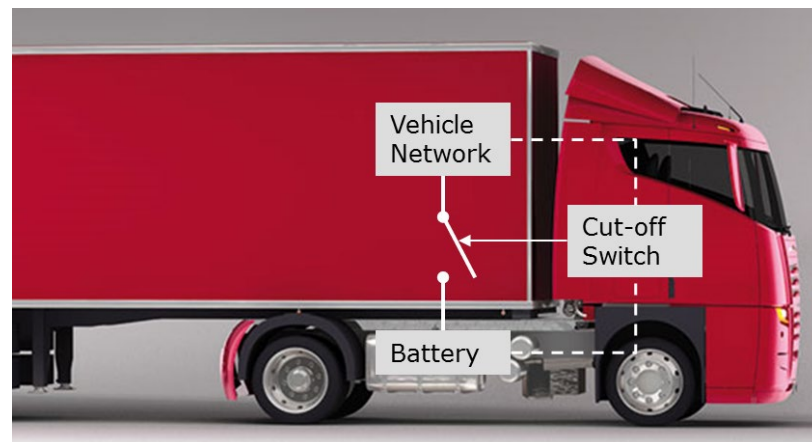
- ▶ Easy cut-off of a vehicle power supply
- ▶ Implementation of regulatory requirement for the transportation of hazardous goods
- ▶ Usage in several vehicle platforms

The Benefit

- ▶ Simple solution of complex requirements
- ▶ One ECU for several vehicle platforms
- ▶ No coding at end of production necessary

The Solution

- ▶ Complete software implementation of a battery cut-off switch
- ▶ Self detection of the used vehicle platform with CAN signals
- ▶ Self diagnostics of the complete ECU



Gateway and Special Function ECU

The Challenge

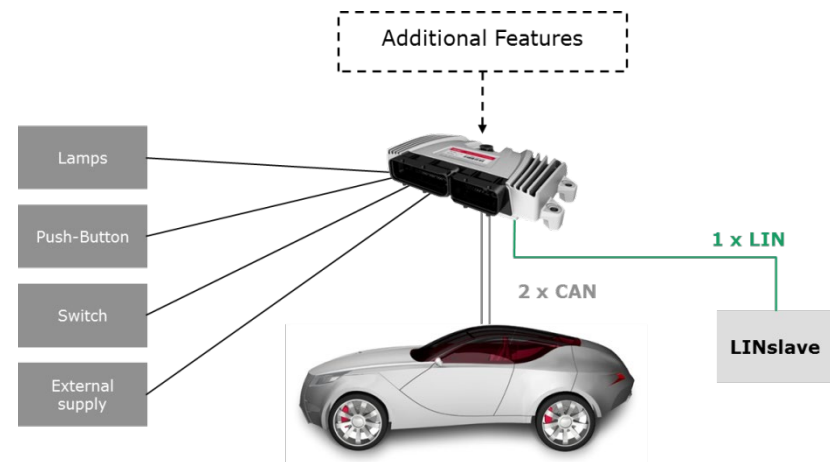
- ▶ Customers first AUTOSAR project
- ▶ Insert new ECU to an existing E/E architecture
- ▶ Short development time
- ▶ Integrate special features on the ECU

The Benefit

- ▶ Short time to market for series vehicle to meet the challenging schedule
- ▶ Understanding of
 - ▶ AUTOSAR processes for series development
 - ▶ AUTOSAR software development

The Solution

- ▶ Use of series-qualified and off-the-shelf ECU
 - ▶ Standard HW for development and series usage
 - ▶ Less population according to customers needs
- ▶ Support customer with
 - ▶ AUTOSAR integration
 - ▶ Software development
 - ▶ Hardware and software testing



Multi-purpose Gateway ECU to extend the existing E/E

The Challenge

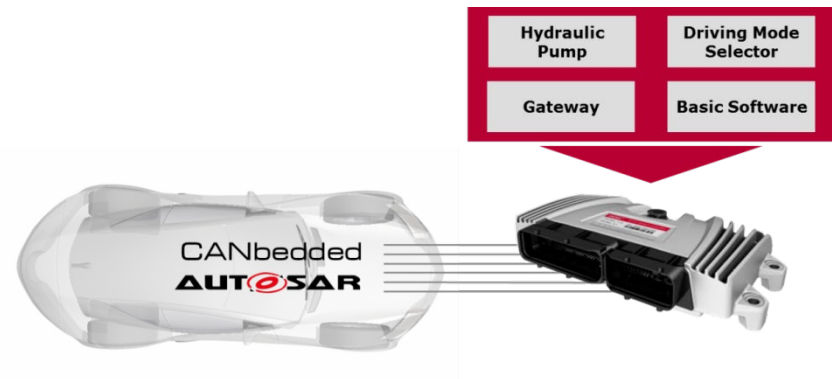
- ▶ Gateway-functionality between
 - ▶ 6 x High-Speed CANs with
 - ▶ CANbedded and AUTOSAR
- ▶ Realization of complex driving mode selector switch
- ▶ Control of a hydraulic pump

The Benefit

- ▶ Plug-and-play solution for existing E/E architecture
- ▶ Quick solution of complex requirements: Basic software, application and series hardware developed by one supplier

The Solution

- ▶ Use of a Vector standard ECU with customer specific adjustments (less-population)
- ▶ Model realization within MATLAB/Simulink®
- ▶ Implementation, integration and verification of the complete ECU through Vector
- ▶ Ongoing maintenance of software for platform adoptions



ECU for Enhanced Dynamic Driving

The Challenge

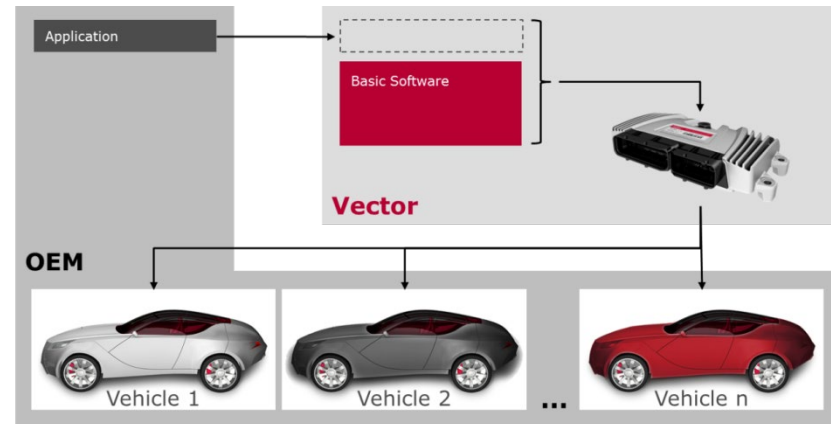
- ▶ Platform ECU development for enhanced vehicle dynamics functions
- ▶ To be used in various car production series

The Benefit

- ▶ Cost-efficient hardware solution (VC)
- ▶ Deep know-how transfer of basic software knowledge to the customer:
 - ▶ Configuration of basic software
 - ▶ Integration of application
- ▶ Usage in different vehicles

The Solution

- ▶ Usage of Vector standard-ECU
- ▶ CANbedded-based software architecture
- ▶ Integration of customer application



Improving Basic Software and Series Hardware

The Challenge

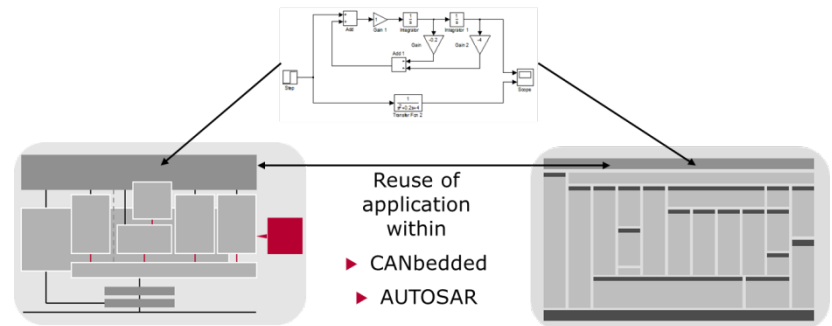
- ▶ OEM requests the change from
 - ▶ Existing hardware to a new ECU
 - ▶ CANbedded to AUTOSAR while keeping the application unchanged

The Benefit

- ▶ Reuse of application without adoptions for future projects
- ▶ Easy access to the AUTOSAR world for customer
- ▶ New, lighter and more cost efficient hardware designed

The Solution

- ▶ Porting of existing ECU architecture to a new and lighter housing, while keeping the performance identically
- ▶ Minor application adjustments to fit both worlds, CANbedded and AUTOSAR



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