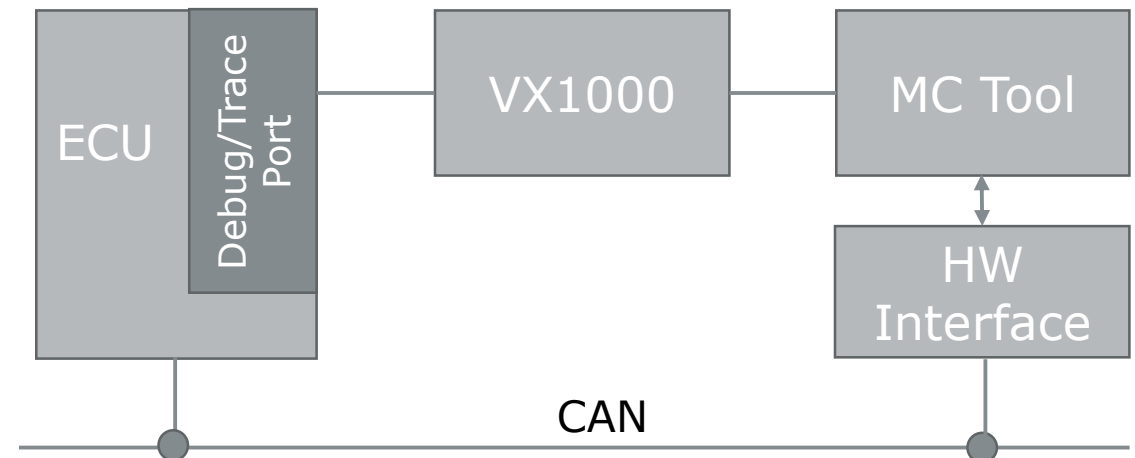
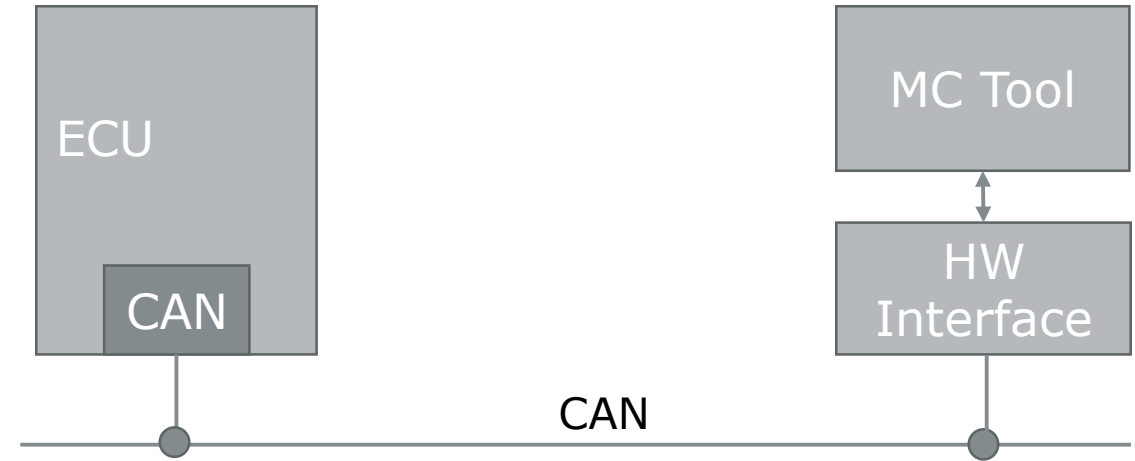


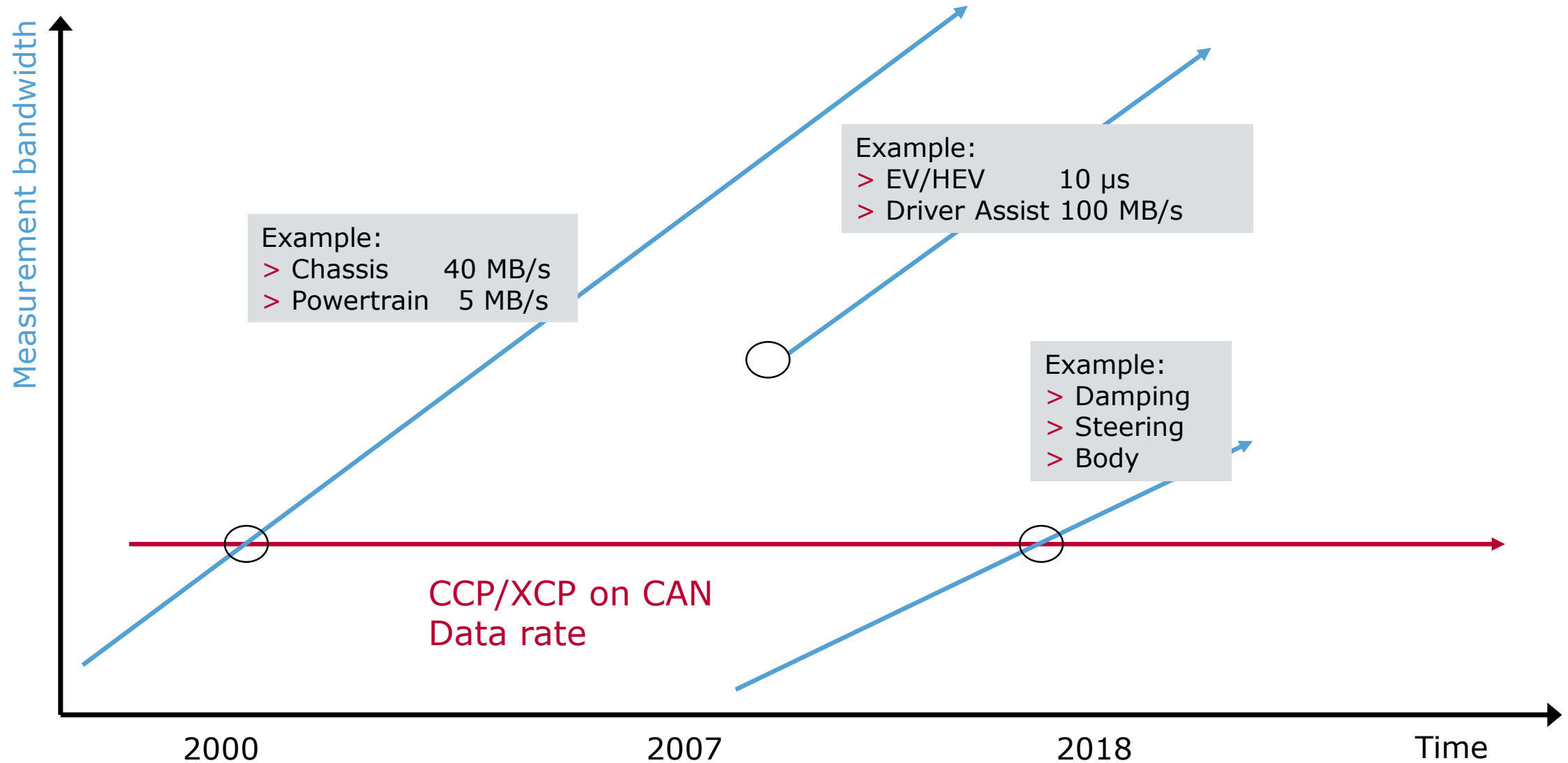
Principle

- ▶ Standard way: over Bus (CAN, LIN, FlexRay ...)
 - ▶ Bottleneck
 - ▶ Few signals
 - ▶ Slow cycles
 - ▶ Influence on bus/ECU performance

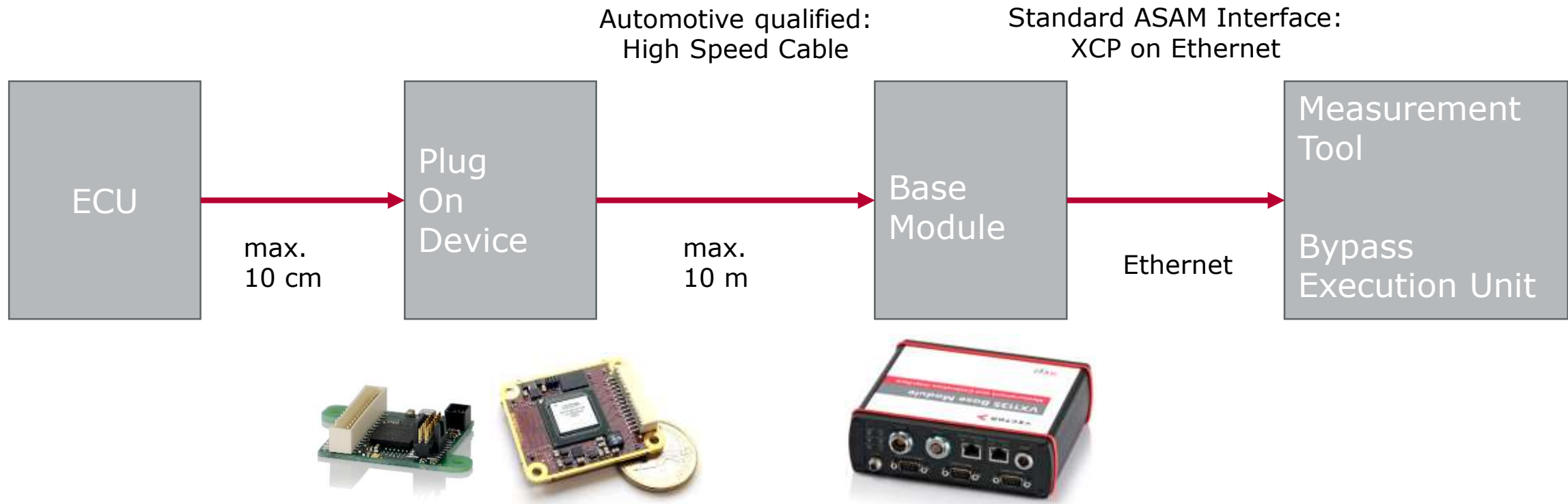
- ▶ Back door: debug and data trace ports
 - ▶ Higher data rates
 - ▶ Up to 100 000 signals
 - ▶ 10 μ s cycles
 - ▶ No influence on bus performance
 - ▶ (No) influence on ECU performance



Measurement Bandwidth for Different Automotive Divisions



Modular Measurement



- ▶ Standard Debug
 - ▶ JTAG / DAP(2) / AUDII / DigRF
- ▶ Trace Ports
 - ▶ RTP / NEXUS / AURORA

- ▶ Two principle measurement concepts
 - ▶ RAM data copy 3 MB/s with μ C load
 - ▶ Data Trace 50 MB/s without μ C load
- ▶ ECU "Cold Start" measurement possible with both concepts

Main Features

- ▶ Measurement: High speed measurement: >100 MB/s (XCP + Streaming)
Fast measurement cycles, up to 100 kHz (10 μ s raster)
First loop data acquisition (Cold start)
- ▶ Calibration: Automatic calibration overlays and CAL page switching
- ▶ Bypassing: Very low latency bypassing
- ▶ Flash Programming: Brain dead flash programming
- ▶ Calibration Data: High speed upload and download
- ▶ CAN support: Integrated 5 x CAN-FD
- ▶ FlexRay support: Optional: Full FlexRay A+B channel
- ▶ Tool Interface: Up to 2 x 1 Gbit/s XCP on Ethernet (ASAM standard)
- ▶ Integrated Eth: Up to 2 x additional BroadR-Reach (100BaseT1) or 100/1000 Standard Ethernet connector

VX1060 Base Module

- ▶ Cost-effective Base Module for VX154x Serial PODs
- ▶ Connector for Debugger access
- ▶ PC uplink: 100 Mbit/s Eth
- ▶ Data rate: up to 10 MB/s
- ▶ Size 115 x 106 x 32 mm

	Serial POD	HSSL POD	HSSL2 POD	CAN/ FlexRay	BR/ ETH
VX1060	•				



VX1132 Base Module

- ▶ ECU interface: Serial or HSSL or HSSL2
- ▶ Connector for Debugger access
- ▶ PC uplink: 1000 Mbit/s Eth
- ▶ Data rate: up to 50 MB/s
- ▶ Max RAM Trace size: 1+1 MB
- ▶ 4 x CAN (Lemo)
- ▶ Optional 1 x FlexRay A+B Monitoring
- ▶ Size 147 x 172 x 55 mm



	Serial POD	HSSL POD	HSSL2 POD	CAN/ FlexRay	BR/ ETH
VX1132B		•		•*	
VX1132C			•		
VX1132H		•			
VX1132S	•			•*	

VX1134 / VX1135 Base Module

- ▶ ECU interface: HSSL2 or HSSL or Serial
- ▶ Data rate: +100 MB/s
(XCP and streaming data)
- ▶ Max RAM Trace size: 8 MB
- ▶ Up to 2 x additional BroadR-Reach
(100BaseT1) or 100/1000 MBit Standard
- ▶ VX1135
 - ▶ 5 x CAN-FD (DSub9)
 - ▶ Optional 1 x Full FlexRay A+B



	Serial POD	HSSL POD	HSSL2 POD	CAN/ FlexRay	BR/ ETH
VX1134B		•			•
VX1134C			•		•
VX1135A	•	•		•	•
VX1135C			•	•	•
VX1135D		•	•	•	•
VX1135E	•			•	2x

VX154x Serial PODs

VX1543A Serial POD

- ▶ Single side PCB, size 23 x 24 x 7 mm
- ▶ Temperature range -40°C to +115°C
- ▶ Optional housing or mounted inside the ECU
- ▶ Standard connectors for DAP and JTAG
- ▶ VX1543A: 1.2V to 5V IO Voltage



VX1544 Serial POD

- ▶ Same footprint and all feature like VX1543A
- ▶ Double Side PCB, with plastic interposer
- ▶ VX1544A/D Support of MPC57xx => DigRF/LFast (320 MHz)
 - ▶ IO Voltage: 0 – 5 V
- ▶ VX1544B Support of Aurix => DAP2 (320 MHz)
 - ▶ IO Voltage: 0 – 3.3 V
- ▶ FlexAdapter and new Serial cable (> 2m) necessary for high frequency
- ▶ Cal-Wake-Up Feature
- ▶ EMEM Power supervision connector



Supported Microcontrollers by Serial PODs

Infineon

- ▶ TriCore TC1xxx (ED) via DAP
- ▶ TriCore AURIX TC2xx (ED) via DAP2 or HSCT
- ▶ TriCore AURIX TC3xx (ED) via DAP2 or HSCT
- ▶ XC2000 Family via DAP

NXP/STM

- ▶ PowerPC xPC5xxx via Nexus JTAG Class 2+ or Zipwire

Renesas

- ▶ RH850 via Nexus JTAG Class 2+
- ▶ V850E2 via Nexus JTAG Class 2+

Performance Data – Serial PODs

Serial PODs			
Target Controller	xPC5xxx, V850, XC2000	TriCore Production Device (PD)	TriCore Emulation Device (ED) Data Trace
Measurement data throughput	≤ 1 MB/s	≤ 3 MB/s (TC1xxx) ≤ 5 MB/s (TC2xx, TC3xx)	≤ 5 MB/s (TC1xxED) ≤ 15 MB/s (TC2xx, TC3xx)
Impact on CPU run-time	≈ 4% per 1 MB/s	≈ 4% per 1 MB/s	0%
DAQ RAM requirement	∅ 3-6 bytes/signal	∅ 3-6 bytes/signal	0 bytes/3 EMEM tiles
DAQ signals	10,000	10,000	100,000
DAQ events	31	31	256
Minimum measurement interval	≈ 65 μs	≈ 18 μs	≈ 10 μs
Bypassing latency time	≤ 400 μs	≤ 400 μs	–

VX145x HSSL PODs

- ▶ Size 40 x 35 x 9 mm
- ▶ Samtec QSH connector
- ▶ Temperature range -40°C to +105°C
- ▶ Optional housing or mounted inside the ECU
- ▶ VX1451: Nexus Aux + RTP/DMM
- ▶ VX1453: Aurora



Supported Microcontrollers by HSSL PODs

Infineon

- ▶ TriCore AURIX TC2xx ED via Aurora
- ▶ TriCore AURIX TC3xx ED via Aurora

NXP/STM

- ▶ PowerPC xPC5xxx via Nexus AUX
- ▶ PowerPC MPC57xx via Nexus Aurora

Renesas

- ▶ RH850 via Nexus Aurora

Texas Instruments

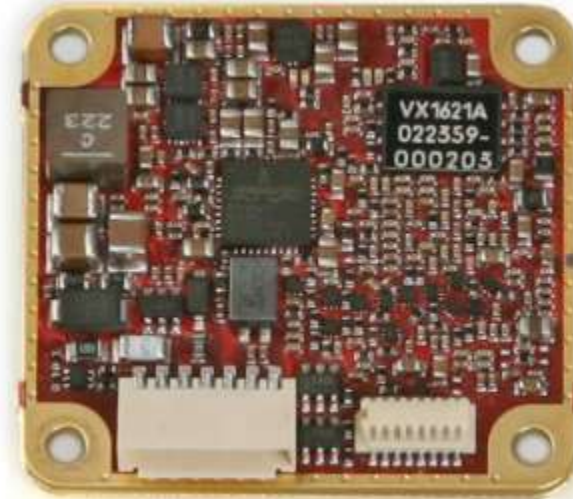
- ▶ TMS570 via RTP/DMM

Performance Data – HSSL PODs

Generic HSSL PODs	
Target Controller	xPC5xxx with Nexus AUX or Nexus Aurora RH850 with Nexus Aurora TC2xx ED, TC3xx ED with Aurora TMSx70 with RTP/DMM
Measurement data throughput	Up to 100 MB/s
Impact on CPU run-time	0%*
Trace window size	2 or 8 MB (VX1132 / VX1135)
DAQ RAM requirement	0 bytes
DAQ signals	100,000
DAQ events	512
Minimum measurement interval	8 μ s
Bypassing latency time	\approx 300 μ s

VX1621A XPOD

- ▶ Standalone measurement and calibration device
- ▶ Standardize XCP protocol support
- ▶ No need for VX1000 Base Module
- ▶ BroadR-Reach / Automotive Eth
- ▶ Requires only simple conductor pair
- ▶ Size 37 x 35 x 9 mm
- ▶ Temperature range -40°C to +120°C



Performance Data – XPOD

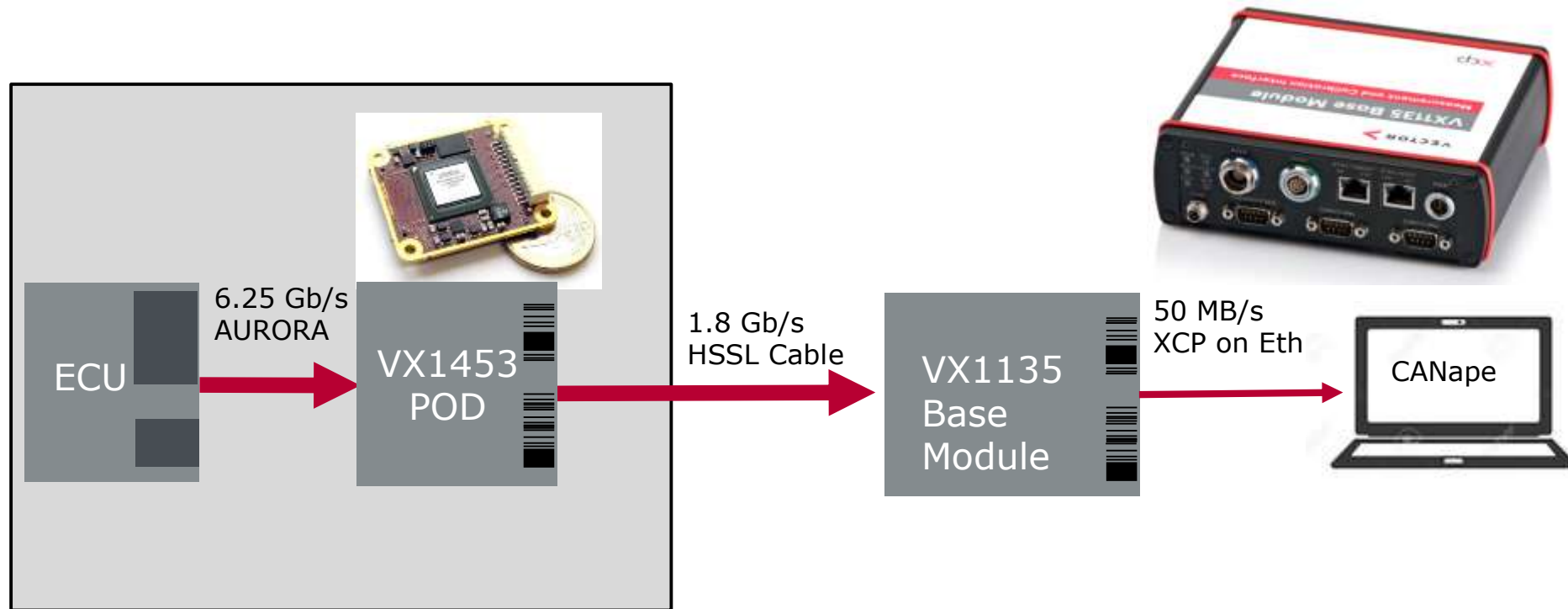
XPOD	
Target Controller	TriCore TC2xx Emulation Device (ED)
Measurement data throughput	≤ 5 MB/s
Impact on CPU run-time	$\approx 4\%$ per 1 MB/s
DAQ RAM requirement	\varnothing 3-6 bytes/signal in EMEM
DAQ signals	10,000
DAQ events	31
Minimum measurement interval	≈ 20 μ s
Bypassing latency time	–

VX0312 Ethernet/CAN Interface

- ▶ 100/1000 Mbit/s (standard Eth)
- ▶ BroadR-Reach (100BASE-T1)
- ▶ CAN/CAN-FD (Lemo)
- ▶ Size 86 x 57 x 26 mm

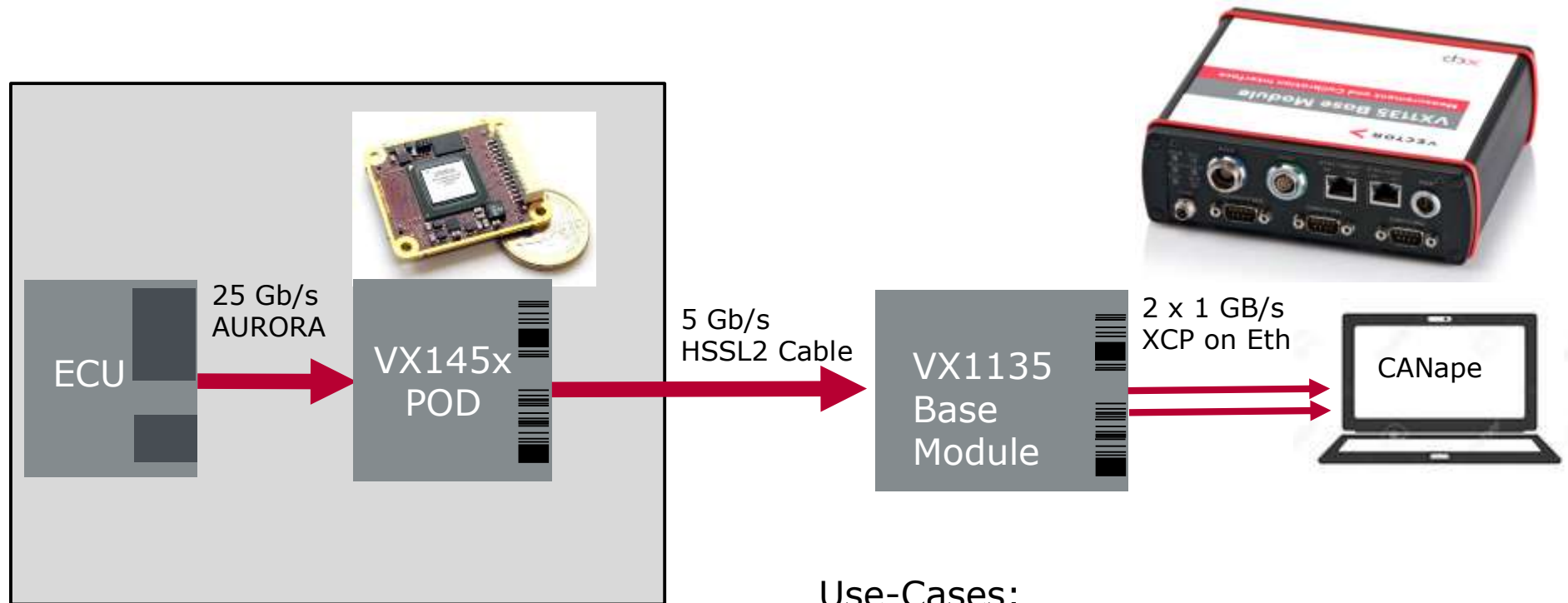


Standard Aurora Data Trace Setup (No CPU load)



- ▶ Current Aurora setup for
 - IFX: 1 x 2.5 Gb/s
 - NXP/STM: 4 x 1.25 Gb/s
 - REN: 2 x 3.125 Gb/s
- ▶ Pins: JTAG/DAP pins + Aurora: up to 2 x 3.1 Gbit
- ▶ Signal prefiltering and 128 MB buffer

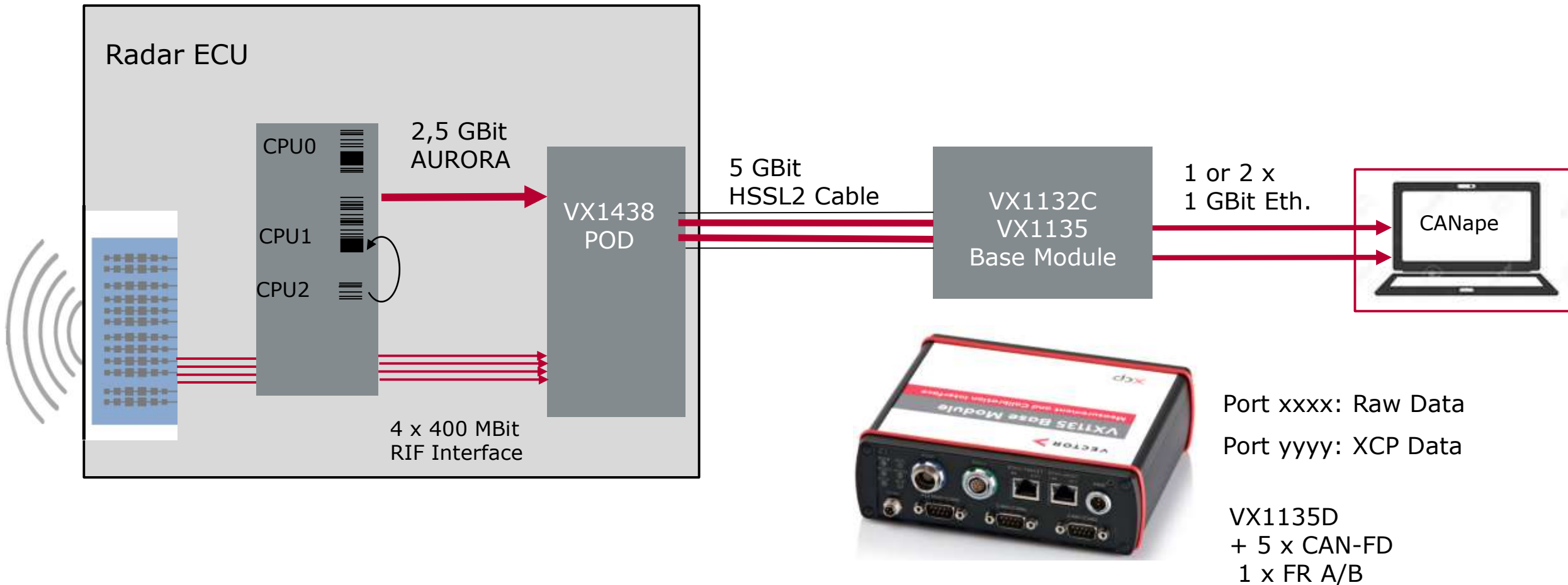
Advanced Aurora Data Trace Setup (No CPU load)





Use-Cases:

- ▶ Next Gen uC : Aurora up to 4 x 6,25 Gbit/s
- ▶ Radar-ECU: Raw Data + XCP Data via Aurora
- ▶ Fusion-ECU: PCIe as an MC interface
- ▶ Fusion-ECU: PCIe + IFX Aurora on one POD

Customer Project : Infineon Aurix Radar Setup: XCP-Data + Radar-Raw Data



Overview: μ C Debug and Data Trace interfaces

ECU-Interface	CPU Type Examples	Interface Frequency	Pins to connect	~ DAQ data rate	Min. cycle time	POD
JTAG/ Nexus Cl.2+	Renesas V850E2 Renesas RH850 FSL MPC55/56xx FSL MPC57xx	20 MHz 20 MHz 20 Mhz 40 MHz	5 JTAG	0,7 MB/s 1,2 MB/s	100 μ s	Serial POD Size: 23 x24 mm VX1543A 
AUDI	Renesas SHx Renesas RH850	4 x 20 MHz	8 AUD	1,5 MB/s	100 μ s	
DAP	Infineon TriCore Aurix / XC2000	80 MHz	2 DAP	2 MB/s	40 μ s	
LFAST/ DigRF	FSL MPC57xx Infineon Aurix	320 MHz	6 DigRF	3 MB/s	40 μ s	VX1544
DAP2	Infineon AurixPD Infineon AurixED	2x160 MHz	3 DAP	3 MB/s Copy 10 MB/s Trace	40 μ s 15 μ s	
Nexus Cl.3	FSL MPC55/6xx	12/16x 80	JTAG + 15 AUX	50 MB/s Trace	10 μ s	HSSL POD Size: 40 x 35 mm 
RTP_DMM	TI TMS570	16x 80 MHz	25 RTP/DMM	VX1451		
Aurora	FSL 57xx ED REN RH850 IFX Aurix ED	4 x 1,2 GHz 2/4 x 3,1 GHz 1 x 2,5 GHz	Aurora up to 4 lanes + JTAG/ DigRF	50 MB/s Trace VX1453	10 μ s	

Key Advantages

- ▶ No need to implement and XCP slave inside your ECU
 - ▶ Better utilization of resources : Memory
- ▶ It is faster because the values are cached and available on internal bus
- ▶ VX driver can be disabled later for SOP
- ▶ In case of XCPonEthernet, additional wiring is needed
- ▶ Ethernet stack will need more resources
 - ▶ Processor time is utilized to process the signals
 - ▶ Memory is needed for the stack itself

For more information about Vector
and our products please visit

www.vector.com

Author:
Mohamad Sah
Vector India